

EXISTENCE AND STABILITY FOR NONLINEAR VARIABLE-COEFFICIENT DIFFERENTIAL EQUATIONS WITH NON-SINGULAR KERNELS

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Abstract. In this work, we study an initial value problem for variable-coefficient differential equation with nonsingular kernel. Firstly, we obtain existence and uniqueness of solutions for the above problem. Secondly, we obtain a stability result within the Ulam-Hyers sense of the given problem. As a special case, we obtain the corresponding conclusions with constant coefficients. An example is provided to verify the theoretical results.

Keywords: Caputo-Fabrizio derivative, variable-coefficient, Ulam-Hyers stability, constant-coefficient.

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1 Introduction

Compared to traditional integer-order equations, fractional differential equations(FDEs), by virtue of the nonlocality of their operators, can accurately characterize complex processes with memory effects and hereditary properties([1, 2]). Therefore, they have become important research tools in fields such as anomalous diffusion, viscoelastic mechanics, soft matter physics, biological system modeling, and control theory([3]).

In 2015, Caputo and Fabrizio proposed a fractional derivative as a modification of the traditional Caputo derivative, which is now known as the Caputo-Fabrizio (CF) derivative([4]). It replaces the power-law kernel in the classical definition with an exponential function. This derivative is extensively applied in modeling across diverse practical domains, including biomedicine, physics

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and engineering, economics and finance, as well as ecology. Research on equations containing the CF derivative has yielded some results ([5, 6, 7, 8, 10, 9, 11, 12]), however, to the best of the authors' knowledge, there is still a great deal of research that has not been addressed. For instance, research on the initial value problem (IVP) for variable-coefficient differential equations involving the CF derivative is scarce.

When the coefficients in the equation are time-varying functions, they can more realistically describe phenomena where memory properties and time-varying characteristics coexist in practical scenarios, such as the dynamic evolution of cells in biophysics or the diffusion of pollutants in environmental science.

Ulam-Hyers (UH) stability serves as a tool for analyzing the error bound between approximate and exact solutions. This theory was introduced by Ulam and Hyers in 1940 ([13, 14]) and has now been widely applied in the study of various types of FDEs. However, its application to variable-coefficient differential equations with the CF derivative remains rare.

In this paper, we study the following initial value problem (IVP) for a variable-coefficient differential equation with nonsingular kernel

$$\begin{cases} {}^{CF}D_{0+}^{\alpha}x(t) + \lambda(t){}^{CF}D_{0+}^{\beta}x(t) = \int_0^t f(s, x(s)) \, ds, & t \in J := [0, T], & (1.1) \\ x(0) = x_0, & & (1.2) \end{cases}$$

where $\alpha, \beta \in (0, 1)$ and $\lambda(t) \in C^1(J, \mathbb{R})$, $\lambda(t) \neq 0$, $(1 - \alpha)\lambda(t) \neq 1 - \beta$, $f(t, x(t))$ will be specified later.

By overcoming the effect of the coefficient $\lambda(t)$, we obtain the existence and uniqueness result for the solution to (1.1)-(1.2), and the UH stability of (1.1). As a special case, we obtain the corresponding results for constant coefficients.

This paper is divided into six sections. Section 2 presents the foundational concepts and properties for later use. In section 3, we obtain the existence and uniqueness of solutions to (1.1)-(1.2). In section 4, we study the UH stability of (1.1). In section 5, we obtain the results for the constant-coefficient case. In section 6, we present the application of the theoretical result.

2 Preliminaries

Throughout this paper, the notation $C(J, \mathbb{R})$ is used for the space of continuous functions on J with the norm $\|x\|_C = \max_{t \in J} |x(t)|$, and $C^1(J, \mathbb{R})$ denotes the space of continuously differential functions on J with the norm $\|x\|_{C^1} = \|x\|_C + \|x'\|_C$.

Definition 2.1 ([6]) Let $0 < \eta \leq 1$. The fractional integral of Caputo-Fabrizio type of a function φ is defined by

$$({}^{CF}I_{0+}^{\eta}\varphi)(t) = (1 - \eta)\varphi(t) + \eta \int_0^t \varphi(s) \, ds, \quad t \geq 0.$$

Clearly, ${}^{CF}I_{0+}^1\varphi(t) = I_{0+}^1\varphi(t) = \int_0^t \varphi(s) \, ds$.

Definition 2.2 ([6]) Let $0 < \eta < 1$. The generalized fractional Caputo-Fabrizio derivative of a function $\varphi : [0, +\infty) \rightarrow \mathbb{R}$ is defined by

$$\begin{aligned} ({}^{CF}D_{0+}^{\eta}\varphi)(t) &= \frac{1}{1-\eta} \int_0^t \varphi'(s) \exp\left(-\frac{\eta(t-s)}{1-\eta}\right) ds \\ &= \frac{1}{1-\eta} [\varphi(t) - \exp\left(-\frac{\eta t}{1-\eta}\right)\varphi(0)] - \frac{\eta}{(1-\eta)^2} \int_0^t \varphi(s) \exp\left(-\frac{\eta(t-s)}{1-\eta}\right) ds. \end{aligned}$$

Remark 2.3 From Definition 2.2, for $\varphi \in C^1(J, \mathbb{R})$, we have

$$\frac{d}{dt} {}^{CF}D_{0+}^{\eta}\varphi(t) = \frac{1}{1-\eta}\varphi'(t) - \frac{\eta}{1-\eta} {}^{CF}D_{0+}^{\eta}\varphi(t), \quad 0 < \eta < 1.$$

Lemma 2.4 ([10]) Let $0 < \eta < 1$ and $\varphi \in C^1(J, \mathbb{R})$. Then

$${}^{CF}I_{0+}^{\eta} {}^{CF}D_{0+}^{\eta}\varphi(t) = \varphi(t) - \varphi(0).$$

Clearly, $I_{0+}^1[\frac{d}{dt}\varphi(t)] = \varphi(t) - \varphi(0)$.

Lemma 2.5 Let $0 < \eta < 1$ and $\varphi \in C^1(J, \mathbb{R})$. Then

$${}^{CF}D_{0+}^{\eta} {}^{CF}I_{0+}^{\eta}\varphi(t) = \varphi(t) - e^{-\frac{\eta t}{1-\eta}}\varphi(0).$$

Proof. From Definitions 2.1 and 2.2, one has

$$\begin{aligned} {}^{CF}D_{0+}^{\eta} {}^{CF}I_{0+}^{\eta}\varphi(t) &= \frac{1}{1-\eta} \int_0^t [(1-\eta)\varphi'(s) + \eta\varphi(s)] \exp\left(-\frac{\eta}{1-\eta}(t-s)\right) ds \\ &= (1-\eta) {}^{CF}D_{0+}^{\eta}\varphi(t) + \int_0^t \varphi(s) d\left(\exp\left(-\frac{\eta}{1-\eta}(t-s)\right)\right) \\ &= \varphi(t) - e^{-\frac{\eta t}{1-\eta}}\varphi(0). \end{aligned}$$

□

Lemma 2.6 Let $\varphi \in C(J, \mathbb{R})$, $0 < \xi, \eta < 1$. Then

$$\begin{aligned} {}^{CF}I_{0+}^{\xi} {}^{CF}I_{0+}^{\eta}\varphi(t) &= {}^{CF}I_{0+}^{\eta} {}^{CF}I_{0+}^{\xi}\varphi(t), \\ {}^{CF}I_{0+}^{\xi} I_{0+}^1\varphi(t) &= I_{0+}^1 {}^{CF}I_{0+}^{\xi}\varphi(t). \end{aligned}$$

Moreover,

$${}^{CF}I_{0+}^{\xi} {}^{CF}I_{0+}^{\eta}\varphi(t) = (1-\eta)(1-\xi)\varphi(t) + (\eta + \xi - 2\eta\xi)I_{0+}^1\varphi(t) + \eta\xi I_{0+}^2\varphi(t).$$

Proof. From Definition 2.1, we have

$$\begin{aligned} {}^{CF}I_{0+}^{\xi} {}^{CF}I_{0+}^{\eta}\varphi(t) &= {}^{CF}I_{0+}^{\xi} \left[(1-\eta)\varphi(t) + \eta I_{0+}^1\varphi(t) \right] \\ &= (1-\xi) \left[(1-\eta)\varphi(t) + \eta I_{0+}^1\varphi(t) \right] + \xi I_{0+}^1 \left[(1-\eta)\varphi(t) + \eta I_{0+}^1\varphi(t) \right] \\ &= (1-\eta) {}^{CF}I_{0+}^{\xi}\varphi(t) + \eta I_{0+}^1 {}^{CF}I_{0+}^{\xi}\varphi(t) = {}^{CF}I_{0+}^{\eta} {}^{CF}I_{0+}^{\xi}\varphi(t). \end{aligned}$$

Likewise, the second relation follows. From Definition 2.1, we can see that

$$\begin{aligned} {}^{CF}I_{0+}^{\xi} {}^{CF}I_{0+}^{\eta} \varphi(t) &= (1 - \xi) {}^{CF}I_{0+}^{\eta} \varphi(t) + \xi I_{0+}^1 {}^{CF}I_{0+}^{\eta} \varphi(t) \\ &= (1 - \xi)[(1 - \eta)\varphi(t) + \eta I_{0+}^1 \varphi(t)] + \xi[(1 - \eta) I_{0+}^1 \varphi(t) + \eta I_{0+}^2 \varphi(t)]. \end{aligned}$$

Then the conclusion can be proved to hold. \square

Theorem 2.7 (Gronwall-Bellman Inequality [15]) *Let $\psi(t)$ and $\theta_2(t)$ be non-negative continuous functions defined on the interval $[a, b]$, and let $\theta_1(t)$ be a non-negative and nondecreasing function. If $\psi(t)$ satisfies the following integral inequality for all $t \in [a, b]$:*

$$\psi(t) \leq \theta_1(t) + \int_a^t \theta_2(s)\psi(s) ds,$$

then it follows that

$$\psi(t) \leq \theta_1(t) \exp\left(\int_a^t \theta_2(s) ds\right), \quad t \in [a, b].$$

3 Existence and uniqueness of solutions

In this section, we present the existence and uniqueness of solution for IVP (1.1)-(1.2).

Theorem 3.1 *If for any $x(t) \in C(J, \mathbb{R})$, $f(t, x(t)) \in C(J, \mathbb{R})$, then $x \in C^1(J, \mathbb{R})$ satisfies (1.1)-(1.2) if and only if $x(t)$ satisfies the following equation*

$$\begin{aligned} x(t) &= -a_1(t) \int_0^t \frac{x(s)}{\lambda(s)} ds + a_2(t) {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds \right] \\ &\quad + a(t) {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} \int_0^t f(s, x(s)) ds \right] + H(t), \end{aligned} \quad (3.1)$$

where $a_1(t)$, $a_2(t)$, $a(t)$, $H(t)$ are defined by

$$a(t) = \frac{(1 - \alpha)\lambda(t)}{1 - \beta + (1 - \alpha)\lambda(t)}; \quad (3.2)$$

$$a_1(t) = \frac{\beta}{1 - \alpha} a(t), \quad a_2(t) = \frac{\alpha}{(1 - \alpha)^2} a(t), \quad (3.3)$$

$$H(t) = a(t)x_0 + \frac{a(t)}{1 - \alpha} {}^{CF}I_{0+}^{\beta} \left[\frac{e^{-\frac{\alpha}{1-\alpha}t}}{\lambda(t)} \right] x_0. \quad (3.4)$$

Proof. Let $x(t)$ satisfy (1.1)-(1.2). By Definition 2.2, we have

$$\frac{1}{1 - \alpha} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x'(s) ds + \lambda(t) {}^{CF}D_{0+}^{\beta} x(t) = \int_0^t f(s, x(s)) ds.$$

By calculation, we obtain

$$\begin{aligned} \frac{1}{1-\alpha}x(t) - \frac{1}{1-\alpha}x_0e^{-\frac{\alpha}{1-\alpha}t} - \frac{\alpha}{(1-\alpha)^2} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)}x(s) \, ds + \lambda(t) \, {}^{CF}D_{0+}^\beta x(t) \\ = \int_0^t f(s, x(s)) \, ds. \end{aligned}$$

This can be rewritten as

$$\begin{aligned} {}^{CF}D_{0+}^\beta x(t) = -\frac{1}{1-\alpha} \frac{x(t)}{\lambda(t)} + \frac{1}{1-\alpha} \frac{x_0}{\lambda(t)} e^{-\frac{\alpha}{1-\alpha}t} \\ + \frac{\alpha}{(1-\alpha)^2} \frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)}x(s) \, ds + \frac{1}{\lambda(t)} \int_0^t f(s, x(s)) \, ds. \end{aligned} \quad (3.5)$$

Applying the operator ${}^{CF}I_{0+}^\beta$ to both sides of the above equation and taking Lemma 2.4 into account, we have

$$\begin{aligned} x(t) = \left\{ 1 + \frac{1}{1-\alpha} {}^{CF}I_{0+}^\beta \left[\frac{e^{-\frac{\alpha}{1-\alpha}t}}{\lambda(t)} \right] \right\} x_0 - \frac{1-\beta}{1-\alpha} \frac{x(t)}{\lambda(t)} - \frac{\beta}{1-\alpha} \int_0^t \frac{x(s)}{\lambda(s)} \, ds \\ + \frac{\alpha}{(1-\alpha)^2} {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)}x(s) \, ds \right] + {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t f(s, x(s)) \, ds \right], \end{aligned} \quad (3.6)$$

which implies

$$\begin{aligned} x(t) = -a_1(t) \int_0^t \frac{x(s)}{\lambda(s)} \, ds + a_2(t) {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)}x(s) \, ds \right] \\ + a(t) {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t f(s, x(s)) \, ds \right] + H(t), \end{aligned}$$

where $H(t)$ is defined by (3.4).

Then we conclude that (3.1) holds. On the other hand, if $x(t)$ satisfies (3.1), then it satisfies (3.6). Applying the operator ${}^{CF}D_{0+}^\beta$ to both sides of (3.6) and taking Lemma 2.5 into account, we have

$$\begin{aligned} {}^{CF}D_{0+}^\beta x(t) = -\frac{1}{1-\alpha} {}^{CF}D_{0+}^\beta {}^{CF}I_{0+}^\beta \frac{x(t)}{\lambda(t)} + \frac{x_0}{1-\alpha} {}^{CF}D_{0+}^\beta {}^{CF}I_{0+}^\beta \left[\frac{e^{-\frac{\alpha}{1-\alpha}t}}{\lambda(t)} \right] \\ + \frac{\alpha}{(1-\alpha)^2} {}^{CF}D_{0+}^\beta {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)}x(s) \, ds \right] + {}^{CF}D_{0+}^\beta {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, x(t)) \right] \\ = -\frac{1}{1-\alpha} \frac{x(t)}{\lambda(t)} + \frac{1}{1-\alpha} \frac{x_0}{\lambda(0)} e^{-\frac{\beta t}{1-\beta}} + \frac{x_0}{1-\alpha} \frac{e^{-\frac{\alpha}{1-\alpha}t}}{\lambda(t)} - \frac{x_0 e^{-\frac{\beta t}{1-\beta}}}{(1-\alpha)\lambda(0)} \\ + \frac{\alpha}{(1-\alpha)^2} \frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)}x(s) \, ds + \frac{1}{\lambda(t)} I_{0+}^1 f(t, x(t)). \end{aligned}$$

This is (3.5), so we can prove that $x(t)$ satisfies (1.1). Obviously, $x(0) = x_0$, the theorem is proved. \square

Next, we study the existence and uniqueness of solutions for IVP (1.1)-(1.2).

Theorem 3.2 *Let $f(t, x(t)) \in C(J, \mathbb{R})$ for any $x(t) \in C(J, \mathbb{R})$. If there exists a function $l_f(t) \in C(J, \mathbb{R}^+)$ such that*

$$|f(t, x_1) - f(t, x_2)| \leq l_f(t)|x_1 - x_2|, \quad \text{for } x_1, x_2 \in \mathbb{R}, \quad (3.7)$$

then (1.1)-(1.2) has a unique solution $x(t) \in C^1(J, \mathbb{R})$.

For convenience, we set

$$\begin{aligned} \|a\|_C &:= a^*, \quad \|a_i\|_C := a_i^*, \quad i = 1, 2, \quad m_\lambda := \min_{t \in [0, T]} |\lambda(t)|, \\ \Lambda &= \frac{1}{m_\lambda} \left[a_1^* + \left(1 - \beta + \frac{\beta T}{2}\right) (a_2^* + a^* \|l_f\|_C) \right]. \end{aligned}$$

Proof. We define an operator $\mathcal{T} : C(J, \mathbb{R}) \rightarrow C(J, \mathbb{R})$ as follows:

$$\begin{aligned} (\mathcal{T}x)(t) &= -a_1(t) I_{0+}^1 \frac{x(s)}{\lambda(s)} + a_2(t) {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds \right] \\ &\quad + a(t) {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, x(t)) \right] + H(t). \end{aligned}$$

Clearly, \mathcal{T} is well-defined and a fixed point of \mathcal{T} is a solution of (3.1).

For $x_1(t), x_2(t) \in C(J, \mathbb{R})$, one obtains

$$\begin{aligned} \left| \int_0^t \frac{x_1(s)}{\lambda(s)} ds - \int_0^t \frac{x_2(s)}{\lambda(s)} ds \right| &\leq \frac{t}{m_\lambda} \|x_1 - x_2\|_C, \\ \left| \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x_1(s) ds - \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x_2(s) ds \right| \\ &\leq \int_0^t |x_1(s) - x_2(s)| e^{-\frac{\alpha}{1-\alpha}(t-s)} ds \leq t \|x_1 - x_2\|_C, \\ |I_{0+}^1 f(t, x_1(t)) - I_{0+}^1 f(t, x_2(t))| &\leq \|l_f\|_C t \|x_1 - x_2\|_C. \end{aligned}$$

Furthermore, we get

$$\begin{aligned} \left| {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x_1(s) ds \right] - {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x_2(s) ds \right] \right| \\ \leq \frac{t(1 - \beta + \frac{\beta T}{2})}{m_\lambda} \|x_1 - x_2\|_C \end{aligned}$$

and

$$\left| {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, x_1(t)) \right] - {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, x_2(t)) \right] \right| \leq \frac{t(1 - \beta + \frac{\beta T}{2}) \|l_f\|_C}{m_\lambda} \|x_1 - x_2\|_C.$$

Thus we have

$$|(\mathcal{T}x_1)(t) - (\mathcal{T}x_2)(t)| \leq \frac{t}{m_\lambda} \left[a_1^* + \left(1 - \beta + \frac{\beta T}{2}\right) (a_2^* + a^* \|l_f\|_C) \right] \|x_1 - x_2\|_C = \Lambda t \|x_1 - x_2\|_C.$$

Since

$$\begin{aligned}
 & \left| \int_0^t \frac{(\mathcal{T}x_1)(s)}{\lambda(s)} ds - \int_0^t \frac{(\mathcal{T}x_2)(s)}{\lambda(s)} ds \right| \leq \frac{\Lambda}{m_\lambda} \frac{t^2}{2} \|x_1 - x_2\|_C, \\
 & \left| \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} (\mathcal{T}x_1)(s) ds - \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} (\mathcal{T}x_2)(s) ds \right| \\
 & \leq \int_0^t |(\mathcal{T}x_1)(s) - (\mathcal{T}x_2)(s)| e^{-\frac{\alpha}{1-\alpha}(t-s)} ds \leq \frac{\Lambda t^2}{2} \|x_1 - x_2\|_C, \\
 & |I_{0+}^1 f(t, (\mathcal{T}x_1)(t)) - I_{0+}^1 f(t, (\mathcal{T}x_2)(t))| \leq \|l_f\|_C \frac{\Lambda t^2}{2} \|x_1 - x_2\|_C,
 \end{aligned}$$

we have

$$\begin{aligned}
 & \left| {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} (\mathcal{T}x_1)(s) ds \right] - {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} (\mathcal{T}x_2)(s) ds \right] \right| \\
 & \leq \frac{\Lambda(1-\beta + \frac{\beta T}{3})}{m_\lambda} \frac{t^2}{2} \|x_1 - x_2\|_C \leq \frac{\Lambda(1-\beta + \frac{\beta T}{2})}{m_\lambda} \frac{t^2}{2} \|x_1 - x_2\|_C
 \end{aligned}$$

and

$$\begin{aligned}
 & \left| {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, (\mathcal{T}x_1)(t)) \right] - {}^{CF}I_{0+}^\beta \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, (\mathcal{T}x_2)(t)) \right] \right| \\
 & \leq \frac{\Lambda(1-\beta + \frac{\beta T}{2})}{m_\lambda} \|l_f\|_C \frac{t^2}{2} \|x_1 - x_2\|_C
 \end{aligned}$$

Then, we have

$$|(\mathcal{T}^2 x_1)(t) - (\mathcal{T}^2 x_2)(t)| \leq \frac{(\Lambda t)^2}{2} \|x_1 - x_2\|_C.$$

By induction, we deduce that

$$|(\mathcal{T}^k x_1)(t) - (\mathcal{T}^k x_2)(t)| \leq \frac{(\Lambda t)^k}{k!} \|x_1 - x_2\|_C.$$

According to the generalized Banach contraction principle, \mathcal{T} has a unique fixed point $x(t) \in C(J, \mathbb{R})$, which is precisely the unique solution of (1.1)–(1.2). \square

4 Stability result

Definition 4.1 Let $f(t, x(t)) \in C(J, \mathbb{R})$ for any $x(t) \in C(J, \mathbb{R})$. Equation (1.1) is UH stable if there is a constant $C_x > 0$ such that for any $\varepsilon > 0$ and for $\hat{u}(t) \in C^1(J, \mathbb{R})$ satisfying

$$\left| {}^{CF}D_{0+}^\alpha \hat{x}(t) + \lambda(t) {}^{CF}D_{0+}^\beta \hat{x}(t) - I_{0+}^1 f(t, \hat{x}(t)) \right| \leq \varepsilon, \quad t \in J, \quad (4.1)$$

there exists a solution $x(t)$ to equation (1.1) with $|x(t) - \hat{x}(t)| \leq C_x \varepsilon$.

Remark 4.2 The function $\hat{x}(t) \in C^1(J, \mathbb{R})$ is a solution of (4.1) if and only if there exists a function $\sigma(t) \in C^1(J, \mathbb{R})$ (depending on $\hat{x}(t)$) such that (i) $|\sigma(t)| \leq \varepsilon$, $t \in J$;
(ii) for $t \in J$, ${}^{CF}D_{0+}^\alpha \hat{x}(t) + \lambda(t) {}^{CF}D_{0+}^\beta \hat{x}(t) - I_{0+}^1 f(t, \hat{x}(t)) = \sigma(t)$.

Theorem 4.3 Let $f(t, x(t)) \in C(J, \mathbb{R})$ for any $x(t) \in C(J, \mathbb{R})$. Then (1.1) is UH stable.

Proof. Let $\hat{x}(t)$ be a solution to (4.1) and $\hat{x}(0) = x_0$, denote

$$\sigma(t) = {}^{CF}D_{0+}^{\alpha} \hat{x}(t) + \lambda(t) {}^{CF}D_{0+}^{\beta} \hat{x}(t) - I_{0+}^1 f(t, \hat{x}(t)),$$

then $|\sigma(t)| \leq \varepsilon$ and $\sigma(0) = 0$. From Theorem 3.1, $\hat{x}(t)$ satisfies

$$\begin{aligned} \hat{x}(t) &= -a_1(t) I_{0+}^1 \frac{\hat{x}(t)}{\lambda(t)} + a_2(t) {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} \hat{x}(s) ds \right] \\ &\quad + a(t) {}^{CF}I_{0+}^{\beta} \left\{ \frac{1}{\lambda(t)} I_{0+}^1 [f(t, \hat{x}(t))] + \frac{\sigma(t)}{\lambda(t)} \right\} + H(t). \end{aligned}$$

We denote by $x(t) \in C^1(J, \mathbb{R})$ the unique solution of IVP (1.1) with (1.2) and

$$\begin{aligned} x(t) &= -a_1(t) I_{0+}^1 \frac{x(t)}{\lambda(t)} + a_2(t) {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds \right] \\ &\quad + a(t) {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, x(t)) \right] + H(t). \end{aligned}$$

Since

$$\begin{aligned} \left| \int_0^t \frac{x(s)}{\lambda(s)} ds - \int_0^t \frac{\hat{x}(s)}{\lambda(s)} ds \right| &\leq \frac{1}{m_{\lambda}} \int_0^t |x(s) - \hat{x}(s)| ds, \\ \left| \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds - \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} \hat{x}(s) ds \right| &\leq \int_0^t |x(s) - \hat{x}(s)| ds, \\ |I_{0+}^1 f(t, x(t)) - I_{0+}^1 f(t, \hat{x}(t))| &\leq \|l_f\|_C \int_0^t |x(s) - \hat{x}(s)| ds, \end{aligned}$$

we get

$$\left| {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} \int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} (x(s) - \hat{x}(s)) ds \right] \right| \leq \frac{1 - \beta + \beta T}{m_{\lambda}} \int_0^t |x(s) - \hat{x}(s)| ds,$$

and

$$\begin{aligned} \left| {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, x(t)) \right] - {}^{CF}I_{0+}^{\beta} \left[\frac{1}{\lambda(t)} I_{0+}^1 f(t, \hat{x}(t)) \right] \right| \\ \leq \frac{(1 - \beta + \beta T) \|l_f\|_C}{m_{\lambda}} \int_0^t |x(s) - \hat{x}(s)| ds. \end{aligned}$$

We deduce

$$|x(t) - \hat{x}(t)| \leq \tilde{\Lambda} \int_0^t |x(s) - \hat{x}(s)| ds,$$

where

$$\tilde{\Lambda} = \frac{1}{m_{\lambda}} \left[a_1^* + (1 - \beta + \beta T)(a_2^* + a^* \|l_f\|_C) \right].$$

By Theorem 2.7, we conclude that

$$|x(t) - \hat{x}(t)| \leq C\varepsilon,$$

where $C := \frac{a^*(1-\beta+\beta T)e^{\tilde{\Lambda}T}}{m_{\lambda}}$. From Definition 4.1, equation (1.1) is UH stable. \square

5 The case of constant coefficients

We first recall Theorem 3.1 in [16], $\alpha = 1$, as follows.

Lemma 5.1 *For any $\mu \in \mathbb{R}$, we have the following results:*

(i) *For any $h \in C(J, \mathbb{R})$, the series $\sum_{k=0}^{\infty} (-\mu)^k I_{0+}^k h(t)$ is convergent and the sum is given by*

$$\sum_{k=0}^{\infty} (-\mu)^k I_{0+}^k h(t) = h(t) - \mu \int_0^t e^{-\mu(t-s)} h(s) ds, \quad t \in J.$$

(ii) *The operator $I + \mu I_{0+}^1 : C[J, \mathbb{R}] \rightarrow C[J, \mathbb{R}]$ is invertible and continuous, and satisfies*

$$(I + \mu I_{0+}^1)^{-1} h(t) = \sum_{k=0}^{\infty} (-\mu)^k I_{0+}^k h(t), \quad t \in J.$$

When $\lambda(t) \equiv \lambda \neq 0$ is a constant, $a(t)$, $a_1(t)$, $a_2(t)$ in (3.2)–(3.3) can be rewritten as

$$a = \frac{(1-\alpha)\lambda}{1-\beta+(1-\alpha)\lambda}, \quad a_1 = \frac{\lambda\beta}{1-\beta+(1-\alpha)\lambda}, \quad a_2 = \frac{\alpha}{1-\alpha} \frac{\lambda}{1-\beta+(1-\alpha)\lambda}. \quad (5.1)$$

Theorem 5.2 *Let $f(t, x(t)) \in C(J, \mathbb{R})$ for any $x(t) \in C(J, \mathbb{R})$. If (3.7) holds, then the IVP*

$$\begin{cases} {}^{CF}D_{0+}^{\alpha} x(t) + \lambda {}^{CF}D_{0+}^{\beta} x(t) = \int_0^t f(s, x(s)) ds, & t \in J := [0, T], \\ x(0) = 0, \end{cases} \quad (5.2)$$

$$x(0) = 0, \quad (5.3)$$

has a unique solution $x(t) \in C^1(J, \mathbb{R})$ satisfying the integral equation

$$x(t) = \frac{1}{D} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \int_0^t e^{-\mu(t-s)} f(s, x(s)) ds,$$

where $D = 1 - \beta + (1 - \alpha)\lambda \neq 0$ and $\mu := \frac{\beta + \lambda\alpha}{D}$.

Proof. By Theorem 3.1, $\lambda(t) \equiv \lambda$, we can deduce that (5.2)–(5.3) is equivalent to the following integral equation

$$x(t) = -\tilde{a}_1 \int_0^t x(s) ds + \tilde{a}_2 {}^{CF}I_{0+}^{\beta} \left[\int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds \right] + \tilde{a} {}^{CF}I_{0+}^{\beta} \left[I_{0+}^1 f(t, x(t)) \right],$$

where

$$\tilde{a} = \frac{a}{\lambda} = \frac{1-\alpha}{D}, \quad \tilde{a}_1 = \frac{a_1}{\lambda} = \frac{\beta}{D}, \quad \tilde{a}_2 = \frac{a_2}{\lambda} = \frac{\alpha}{D(1-\alpha)}. \quad (5.4)$$

Applying ${}^{CF}I_{0+}^{\alpha}$ to both sides of the above equation and combining with

$$-\tilde{a}_1 {}^{CF}I_{0+}^{\alpha} \int_0^t x(s) ds = -\tilde{a}_1 \left[(1-\alpha) \int_0^t x(s) ds + \alpha \int_0^t \int_0^s x(\tau) d\tau ds \right]$$

and

$$\begin{aligned} {}^{CF}I_{0+}^{\alpha} \left[\int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds \right] &= (1-\alpha) \int_0^t x(s) e^{-\frac{\alpha}{1-\alpha}(t-s)} ds + \alpha \int_0^t \int_0^s x(\tau) e^{-\frac{\alpha}{1-\alpha}(s-\tau)} d\tau ds \\ &= (1-\alpha) \int_0^t x(s) ds, \end{aligned}$$

we find

$$\begin{aligned} {}^{CF}I_{0+}^{\alpha} x(t) &= -\tilde{a}_1 \left[(1-\alpha) \int_0^t x(s) ds + \alpha \int_0^t \int_0^s x(\tau) d\tau ds \right] \\ &\quad + \tilde{a}_2 {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \left[\int_0^t e^{-\frac{\alpha}{1-\alpha}(t-s)} x(s) ds \right] + \tilde{a} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \left[I_{0+}^1 f(t, x(t)) \right] \\ &= -\tilde{a}_1 \left[(1-\alpha) \int_0^t x(s) ds + \alpha \int_0^t \int_0^s x(\tau) d\tau ds \right] \\ &\quad + \tilde{a}_2 (1-\alpha) {}^{CF}I_{0+}^{\beta} \int_0^t x(s) ds + \tilde{a} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \left[I_{0+}^1 f(t, x(t)) \right] \\ &= -\tilde{a}_1 \left[(1-\alpha) \int_0^t x(s) ds + \alpha \int_0^t \int_0^s x(\tau) d\tau ds \right] \\ &\quad + \tilde{a}_2 (1-\alpha)(1-\beta) \int_0^t x(s) ds + \tilde{a}_2 (1-\alpha)\beta \int_0^t \int_0^s x(\tau) d\tau ds \\ &\quad + \tilde{a} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \left[I_{0+}^1 f(t, x(t)) \right] \\ &= \frac{\alpha-\beta}{D} \int_0^t x(s) ds + \tilde{a} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \left[I_{0+}^1 f(t, x(t)) \right]. \end{aligned}$$

Therefore

$$\left(I + \frac{\beta + \lambda\alpha}{D} I_{0+}^1 \right) x(t) = \frac{1}{D} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \left[I_{0+}^1 f(t, x(t)) \right]. \quad (5.5)$$

By Lemma 5.1, we obtain

$$\begin{aligned} x(t) &= \frac{1}{D} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \sum_{k=0}^{\infty} (-\mu)^k I_{0+}^{k+1} f(t, x(t)) \\ &= \frac{1}{D} {}^{CF}I_{0+}^{\beta} {}^{CF}I_{0+}^{\alpha} \int_0^t e^{-\mu(t-s)} f(s, x(s)) ds. \end{aligned}$$

□

6 Applications

Example 6.1 We consider the following IVP

$$\begin{cases} {}^{CF}D_{0+}^{\frac{1}{2}} x(t) + e^t {}^{CF}D_{0+}^{\frac{1}{3}} x(t) = \int_0^t \frac{s^2 x(s)}{1+x^2(s)} ds, & t \in [0, 1], \\ x(0) = 2. \end{cases} \quad (6.1)$$

$$(6.2)$$

For

$$\alpha = \frac{1}{2}, \quad \beta = \frac{1}{3}, \quad x_0 = 2, \quad T = 1, \quad \lambda(t) = e^t, \quad f(t, x(t)) = \frac{t^2 x(t)}{1+x^2(t)},$$

we can rewrite (6.1)–(6.2) as IVP (1.1)–(1.2). Clearly, for $x \in C(J, \mathbb{R})$, $f(t, x(t)) \in C(J, \mathbb{R})$. Since

$$\frac{|1 - x_1 x_2|}{(1 + x_1^2)(1 + x_2^2)} \leq \frac{\sqrt{(1 + x_1^2)(1 + x_2^2)}}{(1 + x_1^2)(1 + x_2^2)} = \frac{1}{\sqrt{(1 + x_1^2)(1 + x_2^2)}} \leq 1,$$

we have

$$|f(t, x_1) - f(t, x_2)| \leq t^2 \cdot \frac{|x_1 - x_2| |1 - x_1 x_2|}{(1 + x_1^2)(1 + x_2^2)} < t^2 |x_1 - x_2|.$$

Now we have satisfied all the assumptions of Theorem 3.2, and it follows that IVP (6.1)–(6.2) has a unique solution $x(t) \in C^1([0, 1], \mathbb{R})$.

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